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## SIMPLIFIED KRIPKE STYLE SEMANTICS FOR MODAL LOGICS K45, KB4 AND KD45

### Abstract

In this paper we show that logics K45, KB4 (= KB5) and KD45 are determined by some classes of simplified Kripke frames without binary accessibility relations between possible worlds. These frames are ordered pairs of sets  $\langle W, A \rangle$ , where  $W$  is a non-empty set of *worlds* and  $A \subseteq W$  (a set of *common alternatives* to all worlds in  $W$ ). From a frame  $\langle W, A \rangle$  we can construct models of the form  $\langle W, A, V \rangle$ , where  $V$  is a standard valuation which to formulae and words assigns truth-values with respect to the set  $A$ . For K45 we use the class of all simplified frames; for KB4 we have the case that  $A = \emptyset$  or  $A = W$ ; and for KD45 we use frames with  $A \neq \emptyset$ .

Moreover, to each of these logics we also assign a suitable class of finite euclidean relational frames which satisfy conditions for normal extensions of K5 presented by Nagle in [2].

*Keywords:* simplified Kripke style semantics, normal modal logics K45, KB4 and KD45.

### 1. Introduction. Preliminaries

Modal formulae are formed in the standard way from the set  $At$  of propositional letters: ' $p$ ', ' $q$ ', ' $p_0$ ', ' $p_1$ ', ' $p_2$ ',  $\dots$ ; the truth-value operators: ' $\neg$ ' and ' $\supset$ ' (negation and material implication); the modal operator ' $\Box$ ' (necessity; the possibility sign ' $\Diamond$ ' is the abbreviation of ' $\neg \Box \neg$ '); and brackets. By  $\mathcal{M}$  we denote the set of modal formulae.

We remind that a set  $\Lambda$  of modal formulae is a *normal modal logic* iff  $\Lambda$  contains all classical tautologies and the following formula

$$\Box(p \supset q) \supset (\Box p \supset \Box q) \quad (\mathbf{K})$$

and  $\Lambda$  is closed under the following rules: modus ponens, necessitation and uniform substitution, i.e. for any  $\varphi, \psi \in \text{For}$

$$\text{if } \varphi \text{ and } \ulcorner \varphi \supset \psi \urcorner \text{ are members of } \Lambda, \text{ so is } \psi, \quad (\mathbf{MP})$$

$$\text{if } \varphi \in \Lambda \text{ then } \ulcorner \Box \varphi \urcorner \in \Lambda, \quad (\mathbf{RN})$$

$$\text{if } \varphi \in \Lambda \text{ then } s\varphi \in \Lambda, \quad (\mathbf{US})$$

where  $s\varphi$  is the result of uniform substitution of formulae for propositional letters in  $\varphi$ . By (US), all these logics include the set PL of all modal formulae which are instances of classical tautologies.

We remind that K is the smallest normal modal logic. For other modal logics we will make use of the following formulae

$$\Box p \supset \Diamond p \quad (\mathbf{D})$$

$$\Box p \supset p \quad (\mathbf{T})$$

$$p \supset \Box \Diamond p \quad (\mathbf{B})$$

$$\Box p \supset \Box \Box p \quad (\mathbf{4})$$

$$\Diamond p \supset \Box \Diamond p \quad (\mathbf{5})$$

Using the names of the formulae above, to simplify naming normal logics, we write  $\mathbf{KX}_1 \dots \mathbf{X}_n$  to denote the smallest normal logic containing the formulae  $(\mathbf{X}_1), \dots, (\mathbf{X}_n)$ . Thus, for example, K5, K45, KB4, KB5, KD45, and KT5 are the smallest normal modal logics which contain, respectively, the following formulae: (5); (4) and (5); (B) and (4); (B) and (5); (D), (4) and (5); (T) and (5). We have  $\mathbf{S5} := \mathbf{KT5} = \mathbf{KTB4} = \mathbf{KDB4} = \mathbf{KDB5}$  and  $\mathbf{KB4} = \mathbf{KB5}$  (cf. e.g. [1], pp. 137 and 139).

For all normal modal logics we may use Kripke *relational frames* of the form  $\langle W, R \rangle$ , where  $W$  is a non-empty set of *worlds* and  $R$  is a binary *accessibility* relation in  $W$ . For a frame  $\langle W, R \rangle$  a *relational model* is any triple  $\langle W, R, V \rangle$  in which  $V: \text{For} \times W \rightarrow \{0, 1\}$  is a function which, to formulae and words, assigns truth-values with respect to  $R$ . This function preserves classical conditions for truth-value operators and for any  $\varphi \in \text{For}$  and  $x \in W$

$$(V_{\square}^R) \quad V(\Box\varphi, x) = 1 \text{ iff } \forall_{y \in R(x)} V(\varphi, y) = 1,$$

where  $R(x) := \{y : x R y\}$ , that is  $R(x)$  is the set of worlds which are accessible from  $x$ .<sup>1</sup>

We say that a formula  $\varphi$  is *valid in a model*  $\langle W, R, V \rangle$  iff  $V(\varphi, x) = 1$  for each  $x$  from  $W$ . A formula is *valid in a frame* iff it is valid in every model on this frame. A formula is *valid in a class of models* (resp. *frames*) iff it is valid in all models (resp. frames) from this class. We say that a normal logic is *determined by* a model (resp. frame; class of models; class of frame) iff all and only formulae in this logic are valid there.

We say that a frame  $\langle W, R \rangle$  (or a model on this frame) is, respectively: *reflexive, serial, symmetric, transitive, Euclidean* iff it satisfies, respectively, the following condition:  $\forall_{x \in W} x R x$ ;  $\forall_{x \in W} \exists_{y \in W} x R y$ ;  $\forall_{x, y \in W} (x R y \iff y R x)$ ;  $\forall_{x, y, z \in W} (x R y \ \& \ y R x \implies x R z)$ ;  $\forall_{x, y, z \in W} (x R y \ \& \ x R z \implies y R z)$ . The logics K, K5, K45, KB4 (= KB5), KD45 and S5 are determined, respectively, by the classes of (cf. e.g. [1]):

- all relational frames,
- Euclidean frames,
- transitive and Euclidean frames,
- symmetric and transitive (symmetric and Euclidean) frames,
- serial, transitive and Euclidean frames,
- reflexive and Euclidean (reflexive, symmetric and transitive; serial, symmetric and transitive) frames.

The facts mentioned in the first paragraph of the abstract have a connection with the well-known fact concerning the logic S5. This logic is also determined by the class of *universal frames* in which all worlds are accessible from all worlds, i.e.  $R = W \times W$  (cf. e.g. [1];  $R$  we also call *universal*). A model  $\langle W, W \times W, V \rangle$  on a universal frame may be identified with the pair  $\langle W, V \rangle$  in which for any  $\varphi \in \text{For}$  and  $x \in W$  we have

$$(V_{\square}^W) \quad V(\Box\varphi, x) = 1 \text{ iff } \forall_{y \in W} V(\varphi, y) = 1.$$

So for the logic S5 we can use models of the form  $\langle W, V \rangle$ .

Similarly, for logics K45, KB4 (=KB5) and KD45 – instead of relational frames – we can use *simplified frames* of the form  $\langle W, A \rangle$ , where  $W$  is a non-empty set of worlds and  $A \subseteq W$  ( $A$  is a set of *common alternatives*

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<sup>1</sup>We say that a relational frame (model) is *empty* iff  $R = \emptyset$ .

to all worlds from  $W$ ). For a frame  $\langle W, A \rangle$  a *simplified model* is any triple  $\langle W, A, V \rangle$  in which  $V: \text{For} \times W \rightarrow \{0, 1\}$  is a function which to formulae and words assigns truth-values with respect to the set  $A$ . This function preserves classical conditions for truth-value operators and, moreover, for any  $\varphi \in \text{For}$  and  $x \in W$

$$(V_{\square}^A) \quad V(\square\varphi, x) = 1 \text{ iff } \forall_{y \in A} V(\varphi, y) = 1.$$

Naturally, also for S5 we can use simplified frames (models) – a special kind in which  $A = W$ . Of course, a simplified model  $\langle W, W, V \rangle$  may be identified with the pair  $\langle W, V \rangle$ .

Of course, for simplified models (frames) and classes of simplified models (frames) we use notions of *valid* and of *determination*, defined similarly as for relational models (frames) and classes of relational models (frames). For logics K45, KB4 and KD45 in Section 2 we prove the following determination theorems with respect to some classes of simplified frames.

- THEOREM 1.1. (i) K45 is determined by the class of all simplified frames.  
(ii) KB4 is determined by the class of «empty» or universal simplified frames, i.e. in which  $A = \emptyset$  or  $A = W$ .  
(iii) KD45 is determined by the class of «non-empty» simplified frames, i.e. in which  $A \neq \emptyset$ .

The facts mentioned in the second paragraph of the abstract have a connection with the following fact concerning normal extensions of the logic K5 which is proved by Nagle in [2].

NAGLE'S FACT 1 ([2], p. 325). *Every normal logic containing (5) is determined by a set of relational frames  $\langle W, R \rangle$  which are finite<sup>2</sup>, Euclidean and satisfy one and only one of the following conditions:*

- (a)  $W$  is a singleton and  $R = \emptyset$ ,
- (b)  $R$  is total in  $W$ , i.e.  $R = W \times W$ ,<sup>3</sup>
- (c) there is a unique «initial» world  $w \in W$  such that  $R$  is total in  $W \setminus \{w\}$  and  $w R x$  for some  $x \in W \setminus \{w\}$ .

In Section 3 for each one of the logics K45, KB4 and KD45 we give and prove some special version of Nagle's Fact.

<sup>2</sup>A frame (model) is said to be *finite* just in case the number of points in  $W$  is finite.

<sup>3</sup>The relation  $R$  is *total* in a set  $X$  iff  $X \times X \subseteq R$ .

## 2. The proof of Theorem 1.1

We begin with the proofs of some facts which will be helpful for the analysis of the logics K45, KB4 and KD45.

LEMMA 2.1. *For any frame  $\langle W, R \rangle$  and  $x \in W$  we put  $W^x := \{x\} \cup A^x$ , where  $A^x := \{y \in W : x R^n y \text{ for some } n > 0\}$ , and  $R^x := R \cap (W^x \times W^x)$ .<sup>4</sup>*

- (i) *If  $R$  is reflexive then  $A^x = W^x$ .*
- (ii) *If  $R$  is serial then  $A^x \neq \emptyset$ .*
- (iii) *If  $R$  is transitive then  $A^x = \{y \in W : x R y\}$ .*
- (iv) *If  $R$  is symmetric, then either  $A^x = W^x$  or  $A^x = \emptyset$ .*
- (v) *If  $R$  is Euclidean, then  $(W^x \setminus \{x\})^2 \subseteq R^x$  and either  $R^x = W^x \times W^x$  or  $R^x \subseteq W^x \times (W^x \setminus \{x\})$ .<sup>5</sup>*
- (vi) *If  $R$  is symmetric and Euclidean, then either  $R^x = W^x \times W^x$  or  $R^x = \emptyset$ .*
- (vii) *If  $R$  is transitive and Euclidean, then*
  - (a) *either  $R^x = W^x \times W^x$  or  $R^x = W^x \times (W^x \setminus \{x\})$ ,*
  - (b)  *$R^x = W^x \times A^x$ .*

PROOF: Points (i)–(iii) are obvious.

(iv) Let  $A^x \neq \emptyset$ . Then for some  $y \in A^x$  we have  $x R y$ . So  $y R x$ , since  $R$  is symmetric. So  $x R^2 x$  and  $x \in A^x$ .

(v) Firstly, let  $y, z \in W^x$  and  $y \neq x \neq z$ . Then by induction we obtain that  $y R z$ . Thus  $(W^x \setminus \{x\})^2 \subseteq R^x$ .

Secondly, also by induction, we obtain that if  $x R x$ , then  $y R z$  for any  $y, z \in W^x$ , i.e.  $R^x = W^x \times W^x$ . If  $\langle x, x \rangle \notin R$ , then  $R^x \neq W^x \times W^x$ . Thus, if  $y R^x z$ , then  $z \neq x$ , since  $R$  is Euclidean. Hence  $y \in W^x$  and  $z \in W^x \setminus \{x\}$ .

(vi) By (iv), either  $A^x = W^x$  or  $A^x = \emptyset$ . If  $A^x = W^x$ , then  $x R x$ ; so  $R^x = W^x \times W^x$ , since  $R$  is Euclidean. If  $A^x = \emptyset$ , then either  $R^x = W^x \times W^x$  or  $R^x = \emptyset$ , by (v).

(vii) Suppose that  $R^x \neq W^x \times W^x$ . Let  $y, z \in W^x$  and  $z \neq x$ . Then, by (iii),  $x R z$  and either  $x = y$  or  $x R y$ . Hence  $y R z$ , since  $R$  is Euclidean. Thus,  $W^x \times (W^x \setminus \{x\}) \subseteq R^x$ . So  $R^x = W^x \times (W^x \setminus \{x\})$ , by (v).

<sup>4</sup> $x R^1 y$  iff  $x R y$ ; and for  $n > 1$ :  $x R^n y$  iff there are  $y_1, \dots, y_{n-1} \in W$  such that  $x R y_1, y_1 R y_2, \dots, y_{n-1} R y$ . Of course,  $\langle W^x, R^x \rangle$  is a frame for generated models.

<sup>5</sup>For this fact see [3], Lemma 1.

(viib) For any  $y, z \in A^x$ ,  $x R y$  and  $x R z$ , by (iii). Hence  $y R z$ , because  $R$  is Euclidean. Thus  $A^x \times A^x \subseteq R$ .

Moreover, by definition of  $A^x$ , we have  $R^x = (R \cap \{\langle x, x \rangle\}) \cup (\{x\} \times A^x) \cup (A^x \times \{x\}) \cup (A^x \times A^x)$ . We consider three cases. Firstly, if  $A^x = \emptyset$ , then  $R^x = R \cap \{\langle x, x \rangle\}$  and  $\langle x, x \rangle \notin R$ , so  $R^x = \emptyset$ . Secondly, if  $A^x \neq \emptyset$  and  $\langle x, x \rangle \notin R$ , then there is no  $y \in A^x$  such that  $y R x$ . So  $A^x \times \{x\} = \emptyset$ . Hence  $R^x = (\{x\} \times A^x) \cup (A^x \times A^x) = (\{x\} \cup A^x) \times A^x$ . Thirdly, if  $A^x \neq \emptyset$  and  $\langle x, x \rangle \in R$ , then  $x \in A^x = W^x$ . Hence  $R^x = \{\langle x, x \rangle\} \cup (\{x\} \times A^x) \cup (A^x \times \{x\}) \cup (A^x \times A^x) = W^x \times W^x$ . In all cases we obtain that  $R^x = W^x \times A^x$ .  $\dashv$

We say that a relation  $R$  in a relational frame  $\langle W, R \rangle$  is *semi-universal* iff  $R = W \times A$  for some  $A \subseteq W$ , i.e. all worlds from  $A$  are accessible from all worlds from  $W$  (in other words,  $A$  is a set of *common alternatives* to all worlds from  $W$ ). We also call these frames *semi-universal*. Notice that:

LEMMA 2.2.

- (i) *All semi-universal relations are transitive and Euclidean.*
- (ii)  *$R$  is reflexive and semi-universal iff  $R = W \times W$ .*
- (iii)  *$R$  is symmetric and semi-universal iff  $R = W \times W$  or  $R = \emptyset = W \times \emptyset$ .*
- (iv)  *$R$  is serial and semi-universal iff  $R = W \times A$  with  $A \neq \emptyset$ .*

We prove that logics K45, KB4 and KD45 are determined by some classes of semi-universal relational frames. For K45 we may use the class of all semi-universal frames (instead of the class of all transitive-Euclidean frames). For KB4 it must be the case that either  $A = W$  or  $A = \emptyset$ , so we may use the class of universal or empty relational frames (instead of the class of all symmetric-transitive frames). Finally, for KD45 it must be the case that  $A \neq \emptyset$ , so we may use the class of non-empty semi-universal frames (instead of the class of all serial-transitive-Euclidean frames).<sup>6</sup>

By Lemma 2.1 we obtain

COROLLARY 2.3. *For any relational frame  $\langle W, R \rangle$ :*

- (i) *If  $R$  is transitive and Euclidean, then  $R^x$  is semi-universal.*
- (ii) *If  $R$  is symmetric and transitive, then  $R^x$  is universal or empty.*
- (iii) *If  $R$  is serial, transitive and Euclidean, then  $R^x$  is non-empty and semi-universal.*

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<sup>6</sup>Thus for these logics we have the like case as for the logic S5 (=KT5 = KTB4), where we may use the class of universal frames instead of the class of all reflexive-Euclidean (i.e. reflexive-transitive-symmetric) frames.

Given the above facts we notice that classes of semi-universal relational models for K45, KB4, and KD45 are connected with some classes of generated models. We make use of models generated from relational models (cf. [1], p. 97).

Let  $\mathcal{M} = \langle W, R, V \rangle$  and  $x \in W$ . Then the model generated by  $x$  from  $\mathcal{M}$  is the relational model  $\mathcal{M}^x = \langle W^x, R^x, V^x \rangle$  in which  $W^x$  and  $R^x$  are as in Lemma 2.1 and for any  $\alpha \in \text{At}$  and  $y \in W^x$  we have  $V^x(\alpha, y) = V(\alpha, y)$ . Of course,  $V^x$  preserves classical conditions for truth-value operators and satisfies the condition  $(V_{\square}^R)$  for  $R^x$ .

For any class  $\mathbf{C}$  of relational models we put the following class of generated models  $\mathcal{G}(\mathbf{C}) := \{\mathcal{M}^x : \mathcal{M} \in \mathbf{C} \text{ and } x \text{ is in } \mathcal{M}\}$ .

FACT 2.4 ([1], Theorems 3.10–3.12). *For any  $\varphi \in \text{For}$*

- (i) *for all  $x$  from  $\mathcal{M}$  and  $y \in W^x$ ,  $V^x(\varphi, y) = V(\varphi, y)$ ;*
- (ii)  *$\varphi$  is valid in  $\mathcal{M}$  iff for every  $x$  in  $\mathcal{M}$ ,  $\varphi$  is valid in  $\mathcal{M}^x$ ;*
- (iii)  *$\varphi$  is valid in  $\mathbf{C}$  iff  $\varphi$  is valid in  $\mathcal{G}(\mathbf{C})$ .* ⊣

From the above facts and facts from p. 165 we obtain

THEOREM 2.5. (i) *The logic K45 is determined by the class of all semi-universal relational frames.*

(ii) *The logic KB4 is determined by the class of universal or empty relational frames.*

(iii) *The logic KD45 is determined by the class of semi-universal relational frames which are non-empty.*

Any semi-universal relational model  $\langle W, W \times A, V \rangle$  may be identified with the triple  $\langle W, A, V \rangle$  in the sense of the following

LEMMA 2.6. *Let  $W$  be a non-empty set,  $A \subseteq W$  and  $v: \text{At} \times W \rightarrow \{0, 1\}$ . Moreover,*

- *let  $\langle W, W \times A, V \rangle$  be a semi-universal model in which  $V$  is the extension of  $v$  (by the condition  $(V_{\square}^R)$  for  $R = W \times A$ );*
- *let  $\langle W, A, V' \rangle$  be a simplified model in which  $V'$  is the extension of  $v$  (by the condition  $(V_{\square}^A)$ ).*

*Then  $V = V'$ , i.e.  $\langle W, W \times A, V \rangle$  may be identified with  $\langle W, A, V' \rangle$ .*

*Remark.* If  $A = W$ , then by Lemma 2.6 the models  $\langle W, W \times A, V \rangle$  and  $\langle W, A, V \rangle$  may be identified with the simplified model  $\langle W, V \rangle$  for S5. ⊣

By Lemma 2.6, any semi-universal model is, essentially, a simplified model which instead of a relation  $W \times A$  has a set  $A$  of *common alternatives to all worlds in  $W$* . From this fact and Theorem 2.5 we obtain Theorem 1.1.

Notice that K45 (resp. KD45) is also determined by the class of simplified frames which are «non-universal» (resp. both «non-empty» and «non-universal»), i.e.  $A \neq W$  (resp.  $\emptyset \neq A \neq W$ ). Indeed, any formula falsifiable in a universal simplified frame  $\langle W, W \rangle$  is also falsifiable in a simplified frame  $\langle W \cup \{x\}, W \rangle$ , where  $x \notin W$ . Thus, all formulae valid in all frames fulfilling  $\emptyset \neq A \neq W$  are also valid in all universal simplified frames.

### 3. Some special version of Nagle's Fact

By the facts from Section 2 and by Nagle's Fact, to each one of the logics K45, KB4 and KD45 we assign a suitable class of finite Euclidean frames which satisfy one and only one of the conditions (a), (b), and a special case of (c) from Nagle's Fact. We have the following

THEOREM 3.1.

- (i) K45 is determined by the class of finite relational frames  $\langle W, R \rangle$  which satisfy one and only one of the following conditions: (a) and (b) from Nagle's Fact, and
  - (c')  $W$  is not a singleton and there is a world  $w \in W$  such that  $R = W \times (W \setminus \{w\})$ .<sup>7</sup>
- (ii) KB4 is determined by the class of finite relational frames  $\langle W, R \rangle$  which satisfy one and only one of the conditions: (a) and (b).
- (iii) KD45 is determined by the class of finite relational frames  $\langle W, R \rangle$  which satisfy one and only one of the conditions: (b) and (c').

In all cases (i)–(iii), either  $R = \emptyset$ , or  $R = W \times W$ , or  $R = W \times (W \setminus \{w\})$ ; so  $R$  is semi-universal, and naturally,  $R$  is transitive and Euclidean.

Notice that K45 (resp. KD45) is also determined by the class of finite relational frames  $\langle W, R \rangle$  which satisfy one of the conditions (a) and (c') (resp. (c') alone). Indeed, any formula falsifiable in a universal frame  $\langle W, W \times W \rangle$  is also falsifiable in a frame  $\langle W \cup \{x\}, (W \cup \{x\}) \times W \rangle$ , where  $x \notin W$ . Thus, all formulae valid in all (c')-frames are also valid in all universal frames.

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<sup>7</sup>The condition (c') is a particular case of the condition (c) from Nagle's Fact. Namely, the relation  $W \times (W \setminus \{w\})$  is total in the non-empty set  $W \setminus \{w\}$  and all worlds from this set are accessible from  $w$ .



Directly from Theorem 3.1 (since  $\emptyset = W \times \emptyset$ ) we obtain the following corollary, which has a connection with Theorem 1.1.

COROLLARY 3.2.

- (i) **K45** is determined by the class of finite simplified frames  $\langle W, A \rangle$  which satisfy one and only one of the following conditions:
  - (a\*)  $W$  is a singleton and  $A = \emptyset$ ,
  - (b\*)  $A = W$ .
  - (c\*)  $W$  is not a singleton and  $A = W \setminus \{w\}$  for some  $w \in W$ .
- (ii) **KB4** is determined by the class of finite simplified frames  $\langle W, A \rangle$  which satisfy one and only one of the conditions (a\*) and (b\*).
- (iii) **KD45** is determined by the class of finite simplified frames  $\langle W, A \rangle$  which satisfy one and only one of the conditions: (b\*) and (c\*).

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